



# Using LiDAR To Estimate Seabird Flight Heights

*Aonghais Cook<sup>1</sup>, Robin Ward<sup>2</sup>, William Sandvej Hansen<sup>3</sup>, Laurids Rolighed Larsen<sup>3</sup> & Jared Wilson<sup>4</sup>*

*<sup>1</sup>BTO, <sup>2</sup>NIRAS Consulting UK, <sup>3</sup>NIRAS Consulting Denmark, <sup>4</sup>Marine Scotland Science*

marinescotland

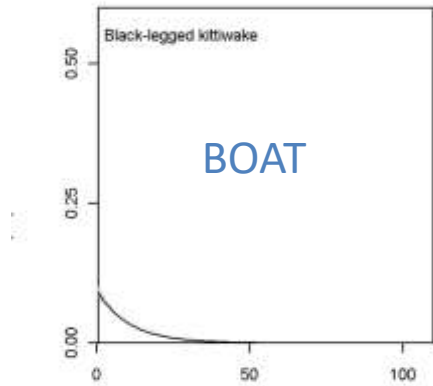


**NIRAS**

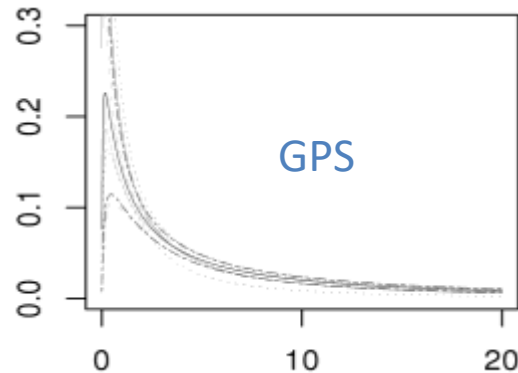


# Seabird flight heights

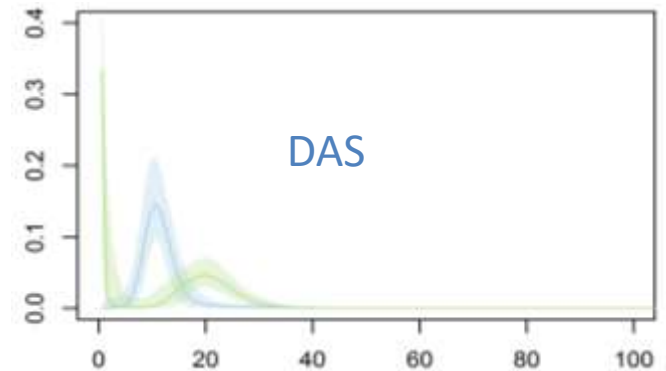
Johnston et al. 2014



Ross-Smith et al. 2014



Johnston & Cook 2016



- Understanding height at which seabirds fly key part of assessing collision risk
- Can be assessed using boat/digital aerial surveys, or GPS tags
- Significant uncertainty surrounding estimates from these platforms
- Patterns vary in both space & time

# LiDAR

- Very precise measurements
- Widely used tool for ecology
  - Habitat mapping
  - Airborne insects
  - Aerial obstructions to aircraft
- Can we use it to measure the heights of seabirds in flight?

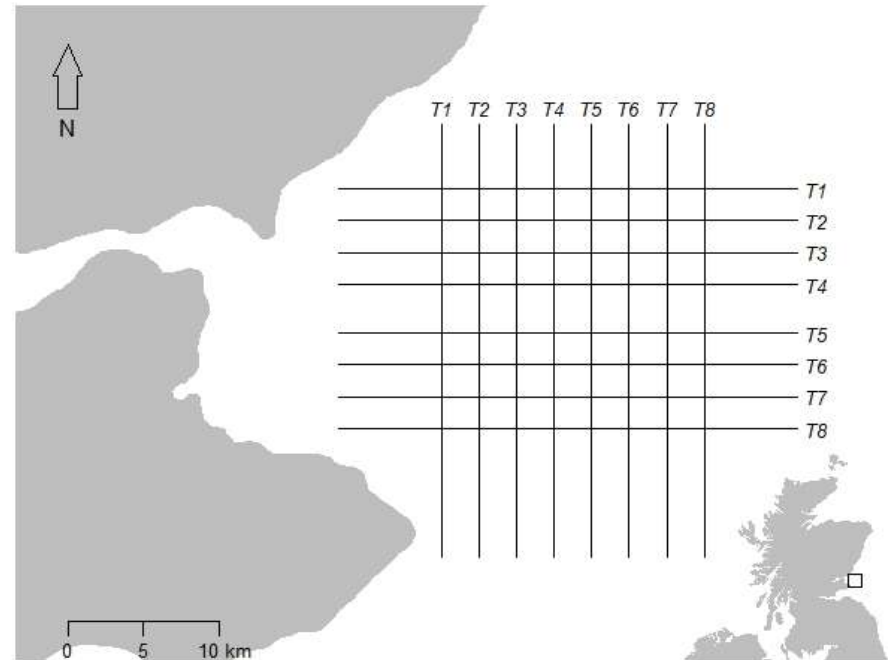
# Validation

- Key question – can it accurately measure heights of moving objects?
- 3 Drones flown at known heights
- Drones detected on every flight
- LiDAR flight height estimates compared to those obtained using drones onboard GPS & photogrammetry techniques
- All estimates within 1m, minimum difference 17 cm



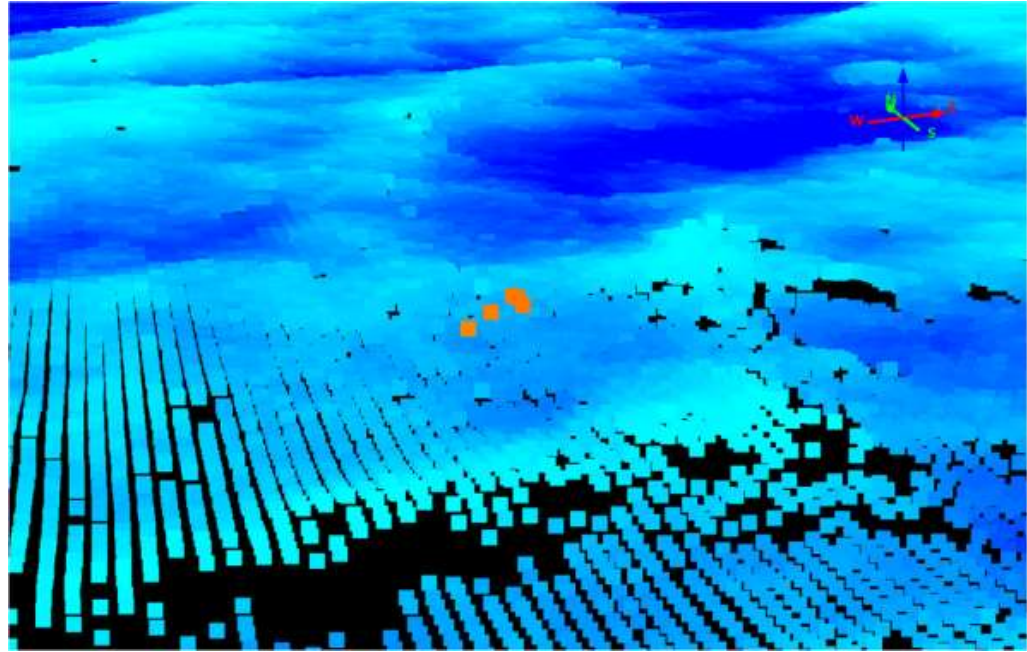
# Surveys

- Aim for minimum 100 birds of each species
- 300m above sea-level & speed of 240 km/h
- LiDAR point density 11 points  $m^{-2}$
- Camera GSD 3.5 cm
- Surveys 20<sup>th</sup> & 22<sup>nd</sup> September 2017
- N-S transects covered once each, E-W transects 3 times each

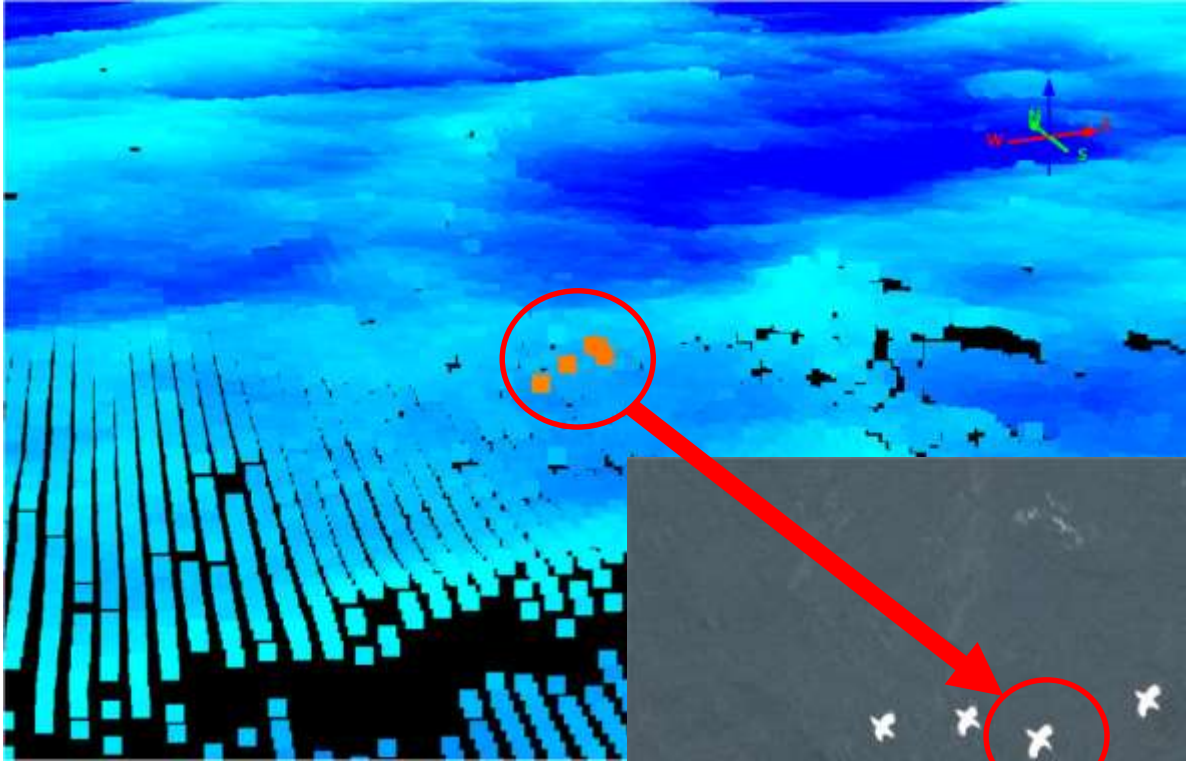


# Image Processing

- Height of every point in the LiDAR cloud measured in relation to European Terrestrial Reference System 89
- Sea surface clutter meant it was necessary to filter out points  $<1-2\text{m}$  above sea level, potential for +ve bias to mean flight height estimates
- Points above 2m identified as birds
- Height estimates independent of height of aircraft



# Image Processing



Points matched to photograph & passed to ornithologist for ID

Speed of aircraft meant each set of points referred to a single bird

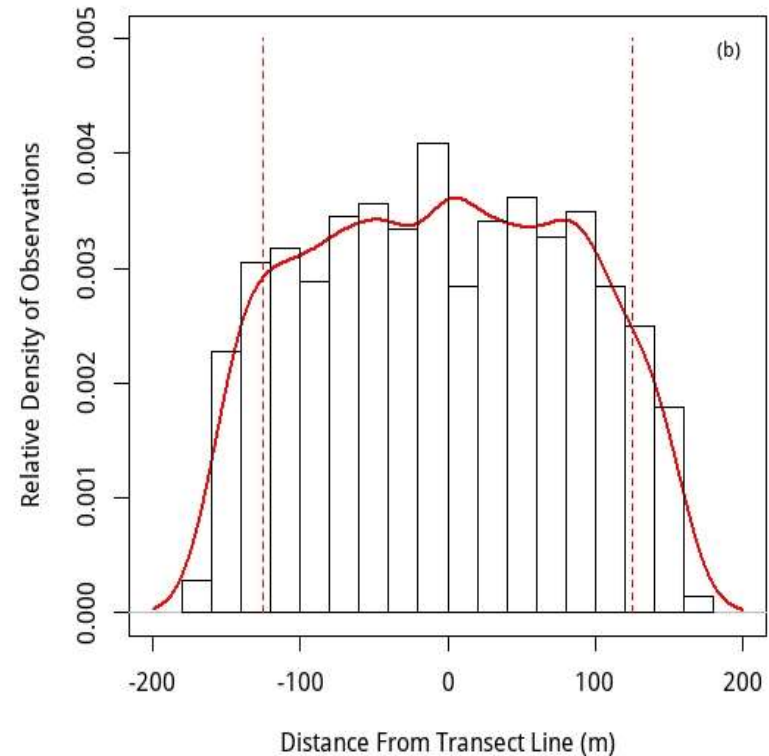
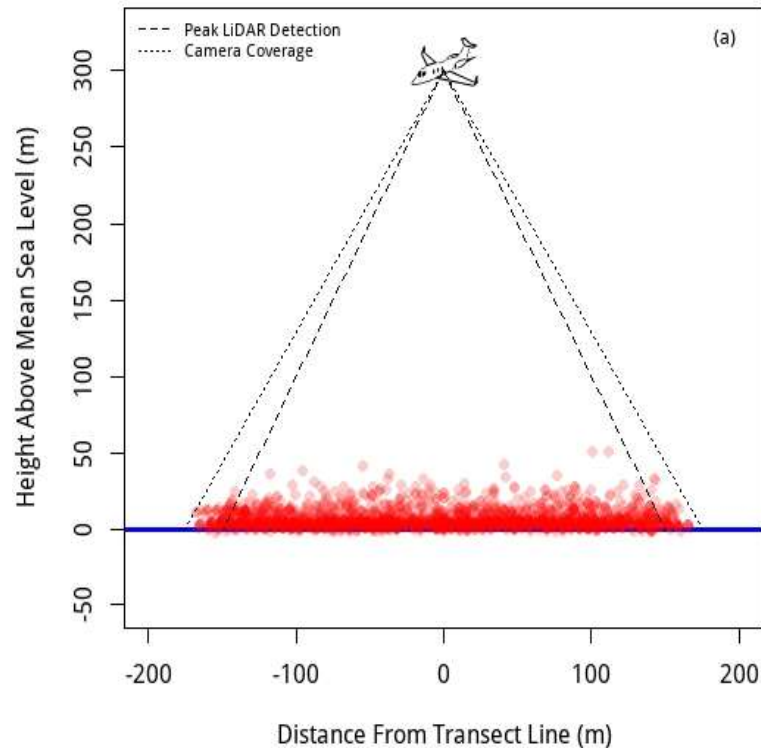


# Species detected

- Over 2,200 birds identified
- Mostly gannets (377) & kittiwakes (806)
- Also, large gulls, auks, terns & great skua
- Issue with vibration in camera images (not sufficiently secured?) meant identifying gulls difficult



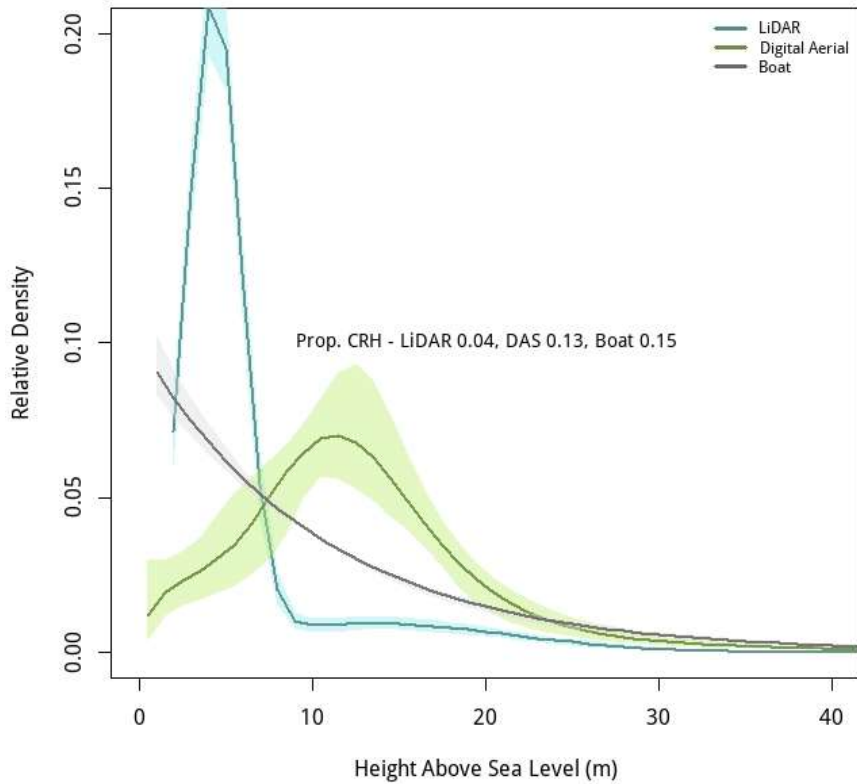
# Flight heights



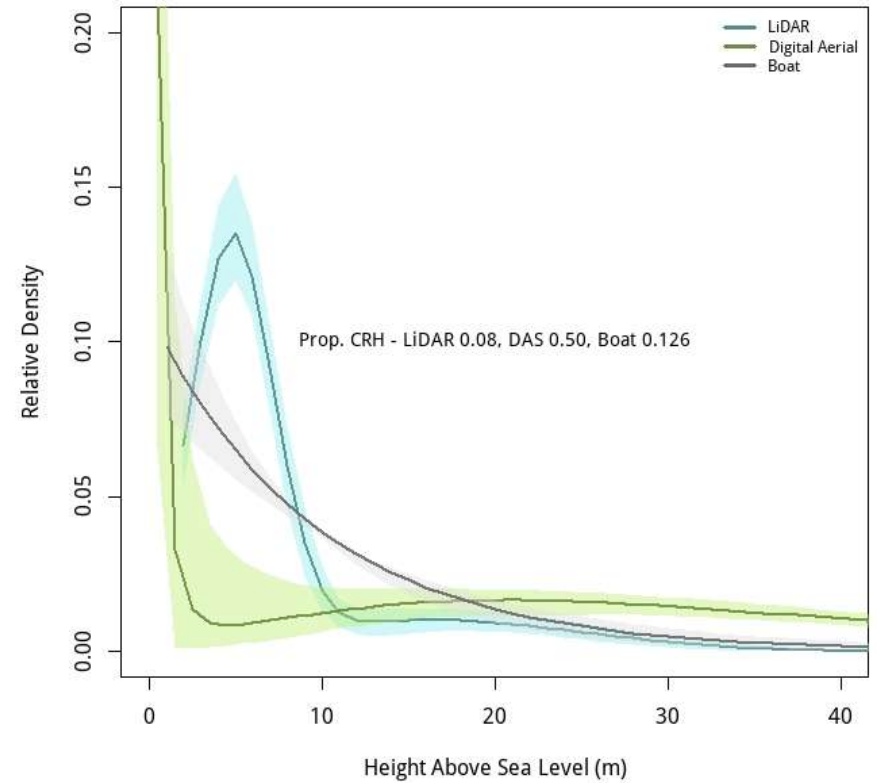
- Potential for birds further from transect line not to be detected when flying at greater altitudes
- Limit analyses to birds within 125m of transect line

# Flight heights

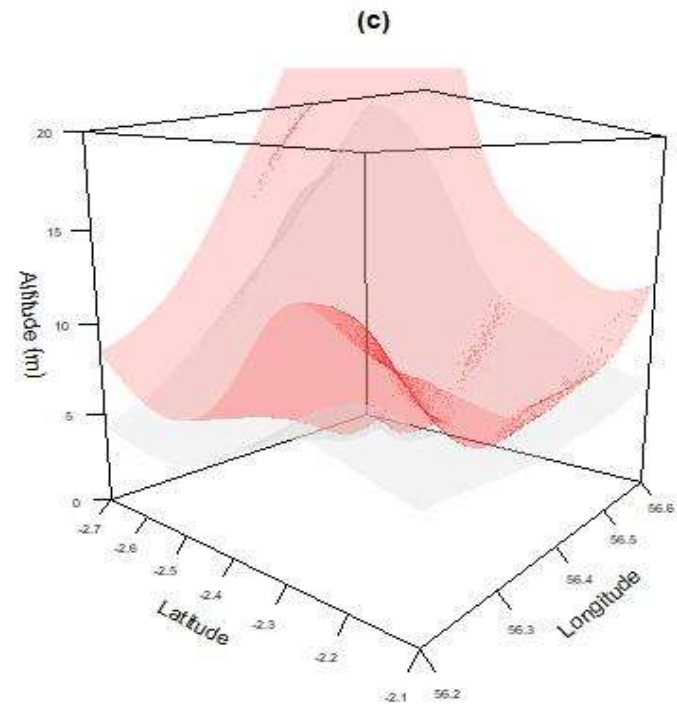
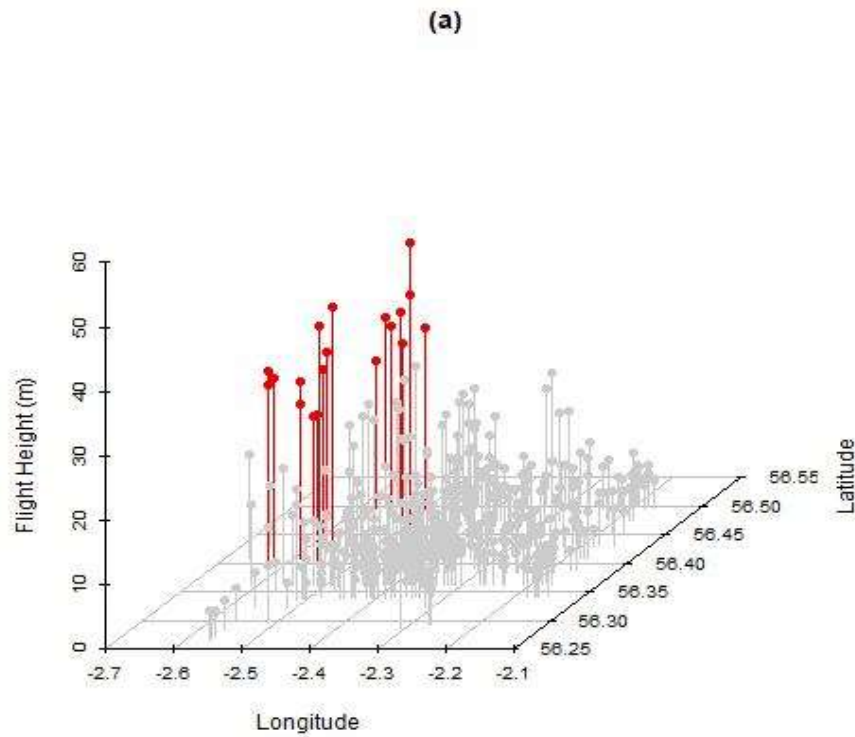
## Kittiwake



## Gannet

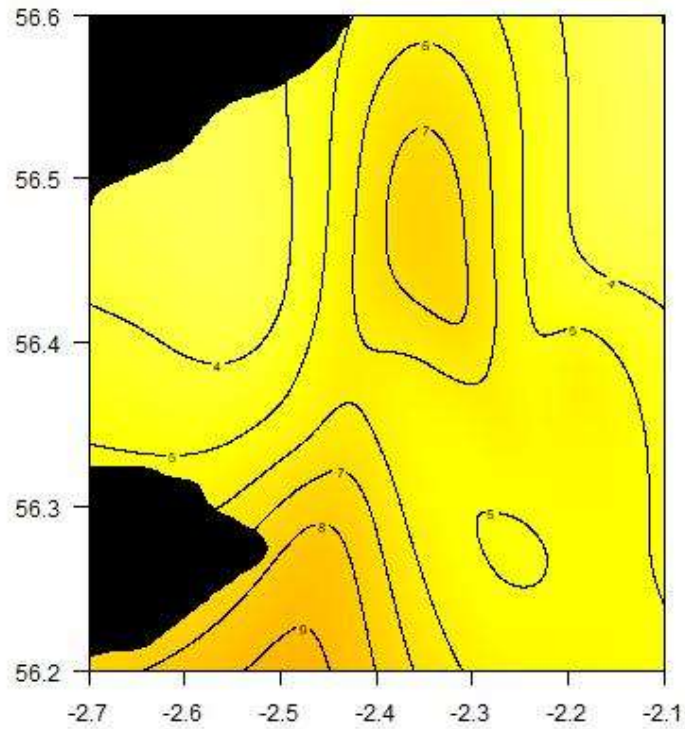


# Flight heights

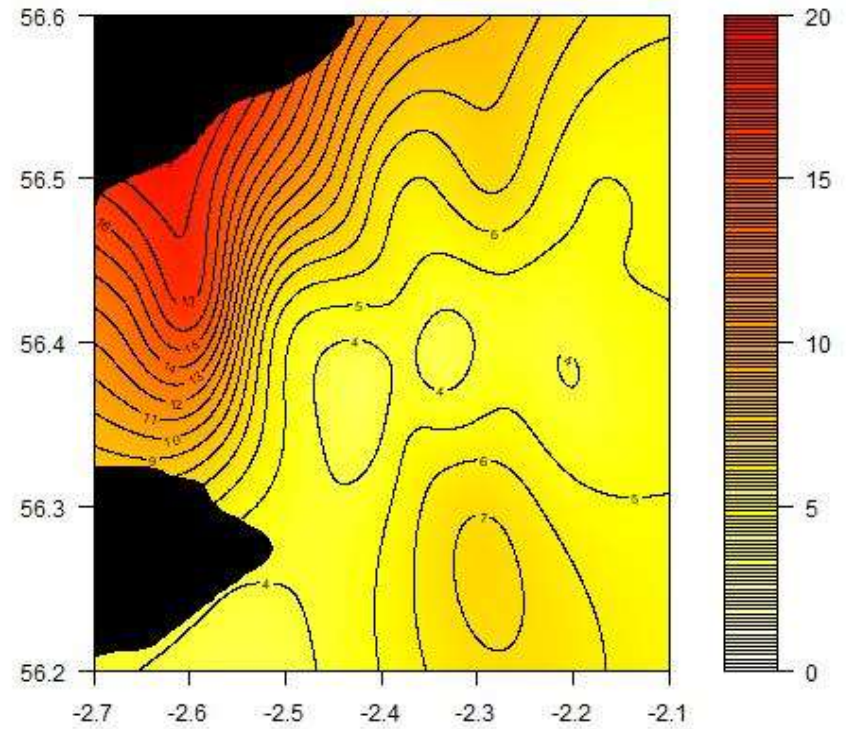


# Flight heights

## Gannet



## Kittiwake



# Conclusions

- LiDAR is an accurate & precise method for measuring seabird flight heights
- Sea clutter means data must be filtered – can detect birds  $> 2\text{m}$  or lower depending on conditions – may be possible to refine this
  - More important for auks etc. than gulls
  - Still precautionary (% birds at CRH will be overestimated)
- Can use data to produce continuous flight height distributions
- Can also look at spatial patterns in bird flight heights

# Acknowledgements

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- Colleagues at BTO & NIRAS for support & advice on this project